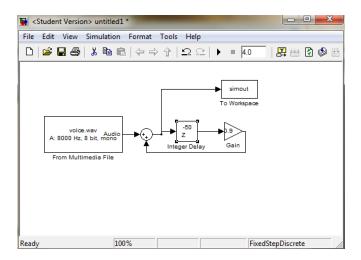
1. The system S2 has an input of y:Integers  $\rightarrow$ Reals and has an output z: Integers  $\rightarrow$ Reals and this is given by  $\forall$  n  $\in$  Integers,  $z(n) = \alpha y(n - N)$ . So we can say:

y(n) = x(n) + z(n) This equation says that this is a feedback system, scaled, delayed.

2. If we put this system into simulink, we have the system shown below.



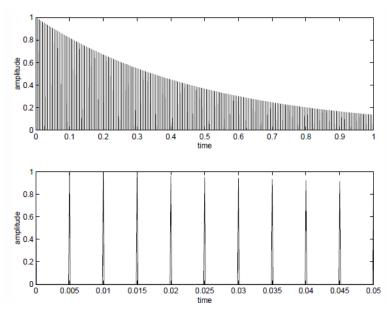
So we have a gain of 0.9 and an N value of 50. If we use a N value of 2000, it tends to echo. If we use N = 50 it's kind of a changed, kind of amplified sound, it is reflecting the sound. The delay bounces around some energy is lost each time it does this. When alpha is greater than 1 it is an unstable system. When alpha is 0, the sound sounds the same as it is the same. When alpha = 1 the sounds echoes forever.

The commands in Matlab plot([0:1/8000:4], simout) xlabel('time'); ylabel('amplitude') will plot this unstable system

3. If we plot the impulse response with N = 40 and alpha = 0.99, we use the commands subplot(2,1,1); plot([0:1/8000:1], simout) xlabel('time'); ylabel('amplitude')

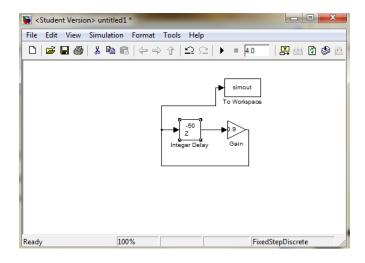
```
subplot(2,1,2); plot([0:1/8000:0.05], simout(1:401))
axis([0, 0.05, 0, 1]);
xlabel('time'); ylabel('amplitude')
```

and we get the plots



This has a period of 0.005 seconds and a frequency of 200 Hz.

4. Our model with a random initial value for our delay values is shown below



It is a richer sound.

5. If we use an input of  $x(n) = ei\omega n$ , then we will have an output of  $y(n) = H(\omega)ei\omega n$ . This will give us  $H(\omega)ei\omega n = ei\omega n + \alpha H(\omega)ei\omega (n-N)$   $= ei\omega n (1 + \alpha H(\omega)e-i\omega N).$ 

And then we can simplify and get

 $H(\omega) = 1/(1 - \alpha e - i\omega N).$ 

Then this can be plotted from 0 to 4 KHz and our omega will vary from 0 to  $2\pi \times 4000/8000 = \pi$ . Then choosing samples or 500 for our amount of samples, we put our commands into Matlab omega = 0:pi/500:pi;

alpha = 0.99;

N = 40;

magnitude = abs(1./(1-alpha\*exp(-i\*omega\*N)));

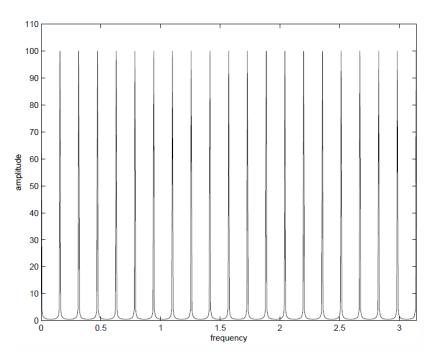
plot(omega, magnitude);

xlabel('frequency');

ylabel('amplitude');

axis([0, pi, 0, 110]);

This gives us the plot



This frequency response tells us our output has a fundamental frequency of 200 Hz with multiples of 200 Hz being our harmonics.